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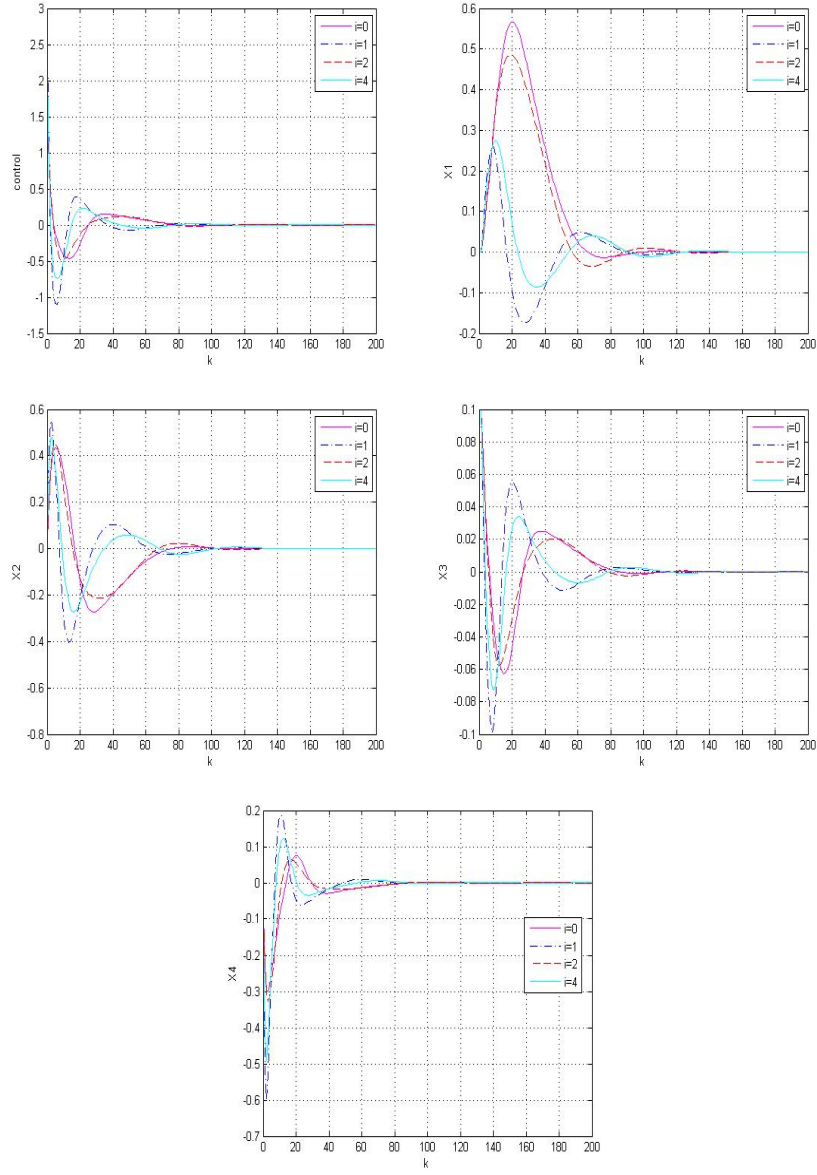


Figure 1: Simulation results of sensitivity approach for trajectory and control in example 2.